

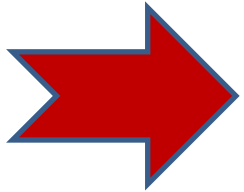
Modeling PFC Converter Using 1200V GaNPower devices



GANPOWER INTERNATIONAL INC

By
Simon Li

Content



Simulation of inductor current control

Circuit implementation

Totem pole PFC

M. Giesselmann and V. Roy, "Modeling Power Factor Correction Circuits with LTSpice," *2018 IEEE International Power Modulator and High Voltage Conference (IPMHVC)*, Jackson, WY, USA, 2018, pp. 162-165, doi: 10.1109/IPMHVC.2018.8936816.

Method: Use of tanh() hysteresis control

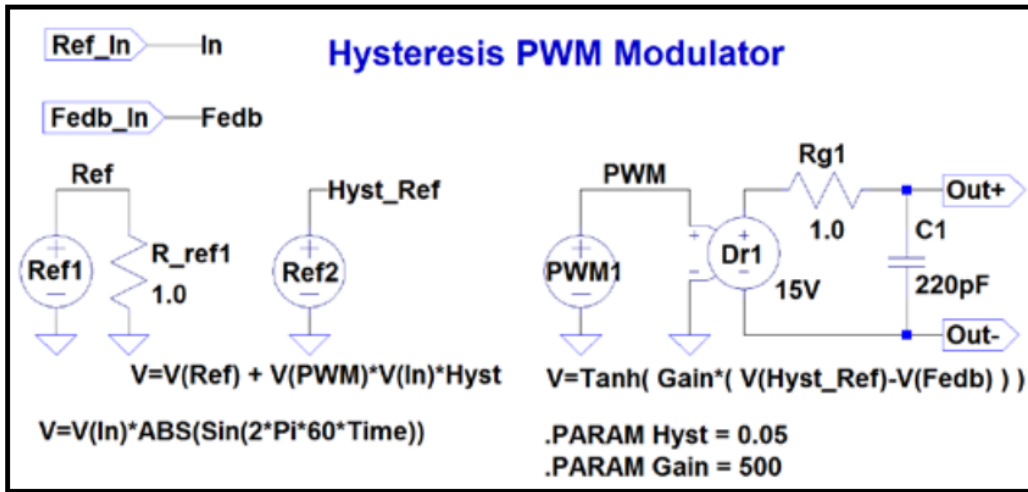


Fig. 6. Schematic of the sub-circuit for the Hysteresis PWM modulator.

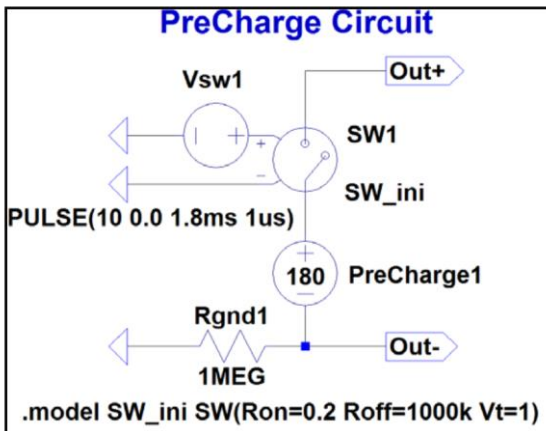
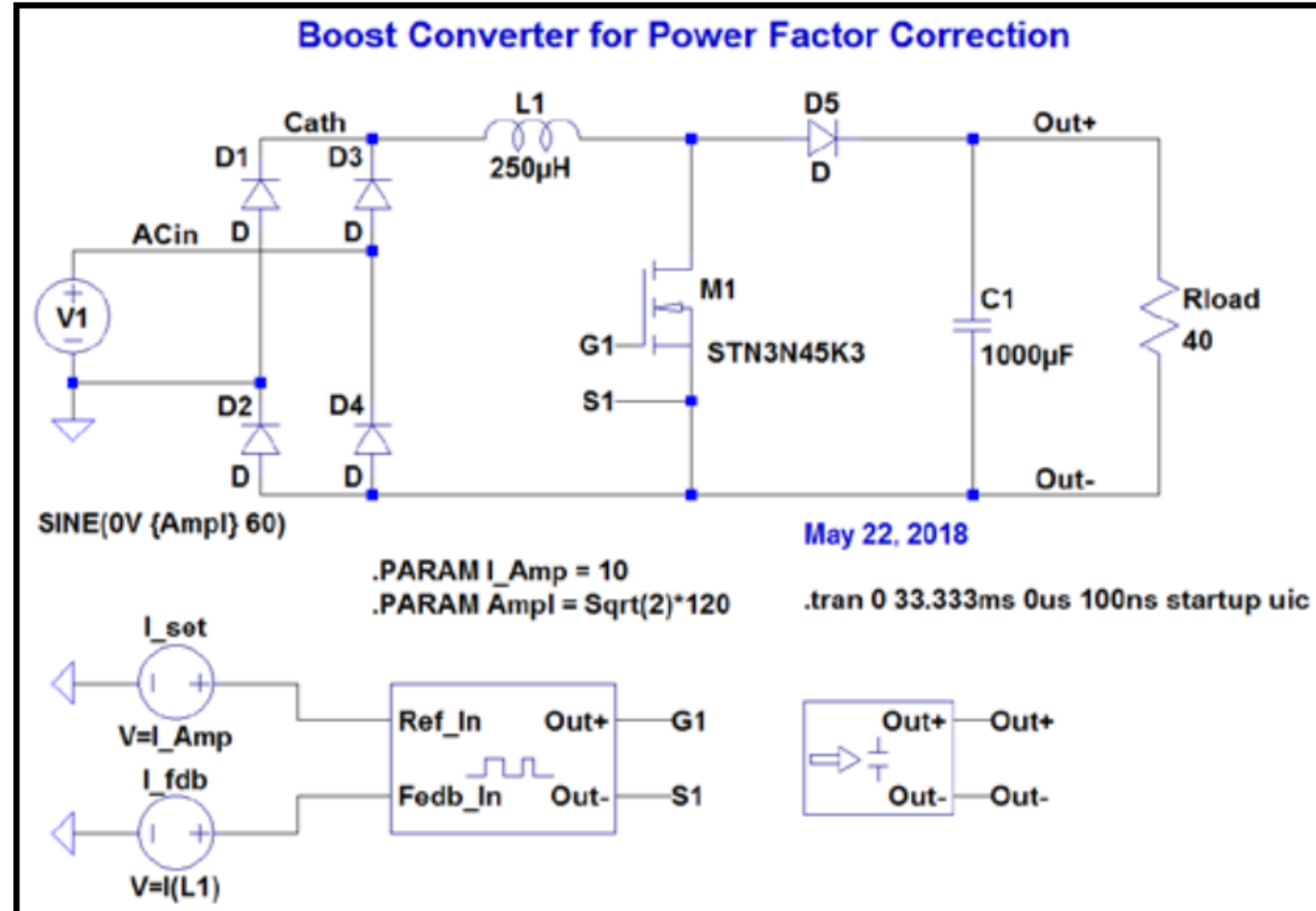
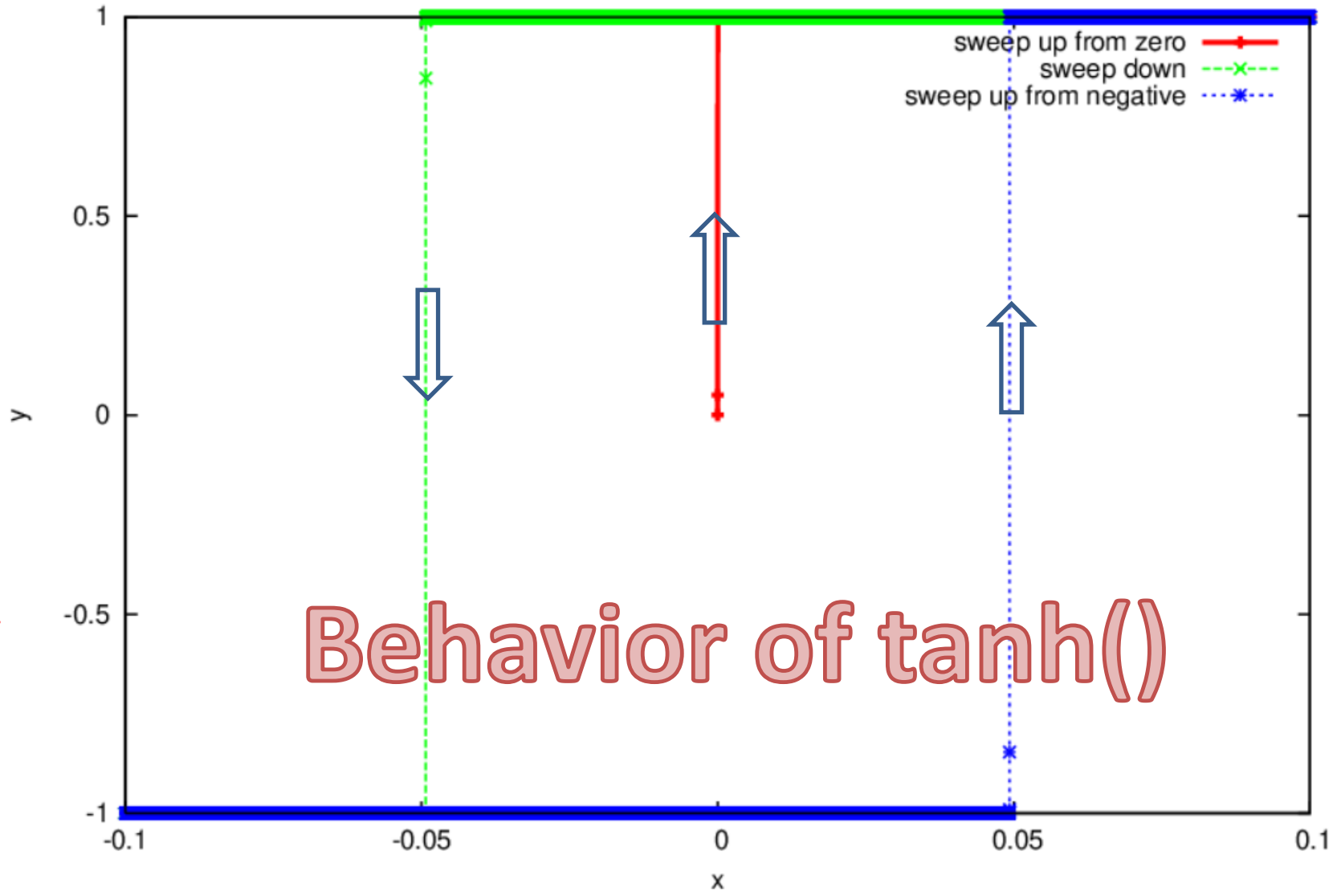


Fig. 2. LTSpice schematic of the Pre-Charge sub-circuit



$$y = \tanh(\text{gain} * (v_in * x + v_in * \text{hyst} * y))$$

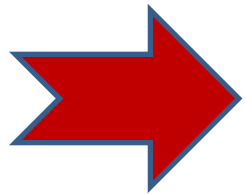


Hyst controls hysteresis transition at +/- hyst

Behavior of tanh()

Content

Simulation of inductor current control



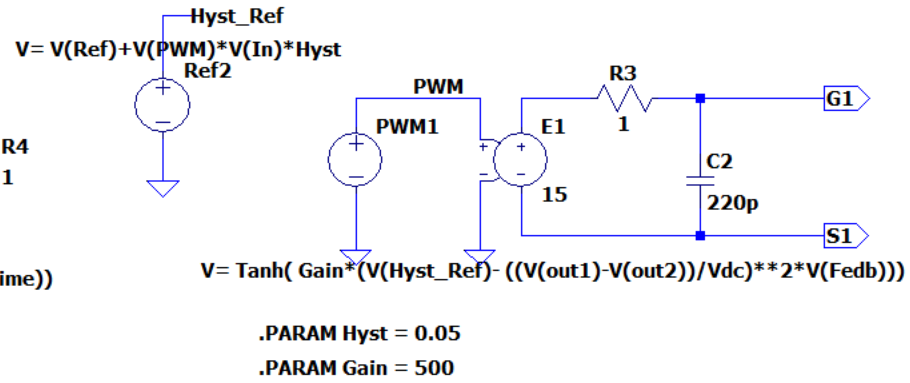
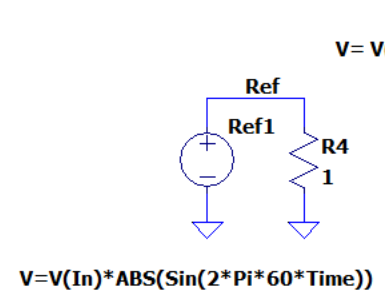
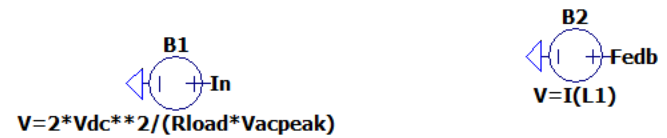
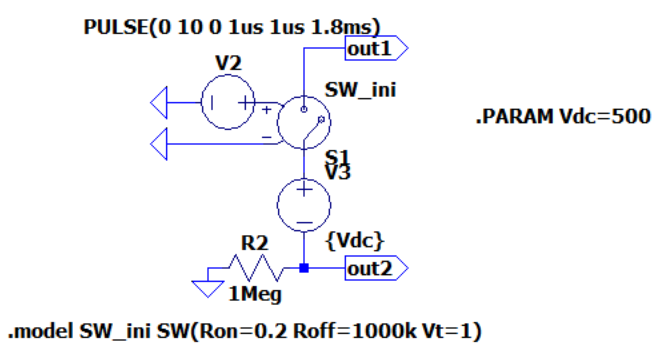
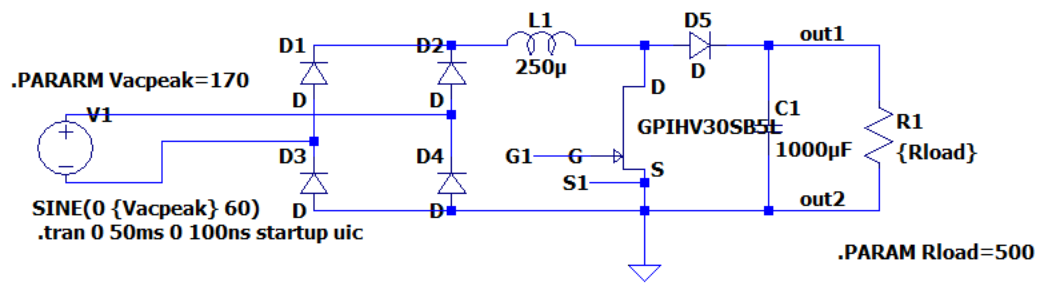
Circuit implementation

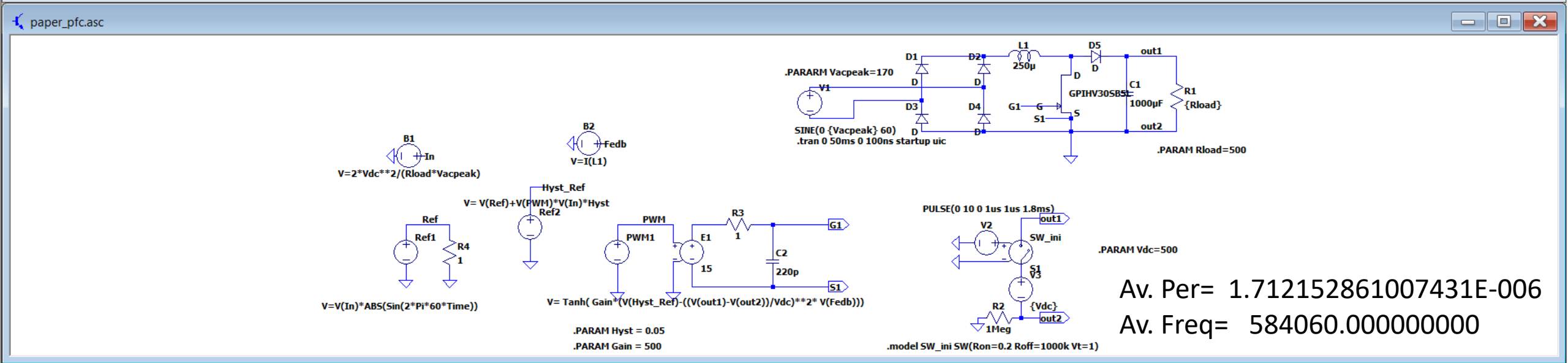
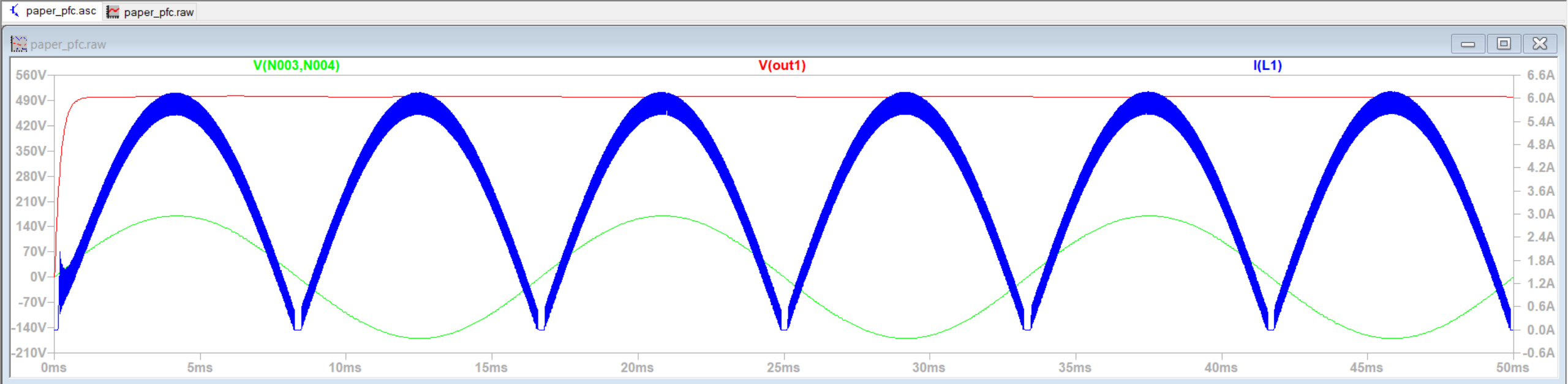
Totem pole PFC

Control Consideration:

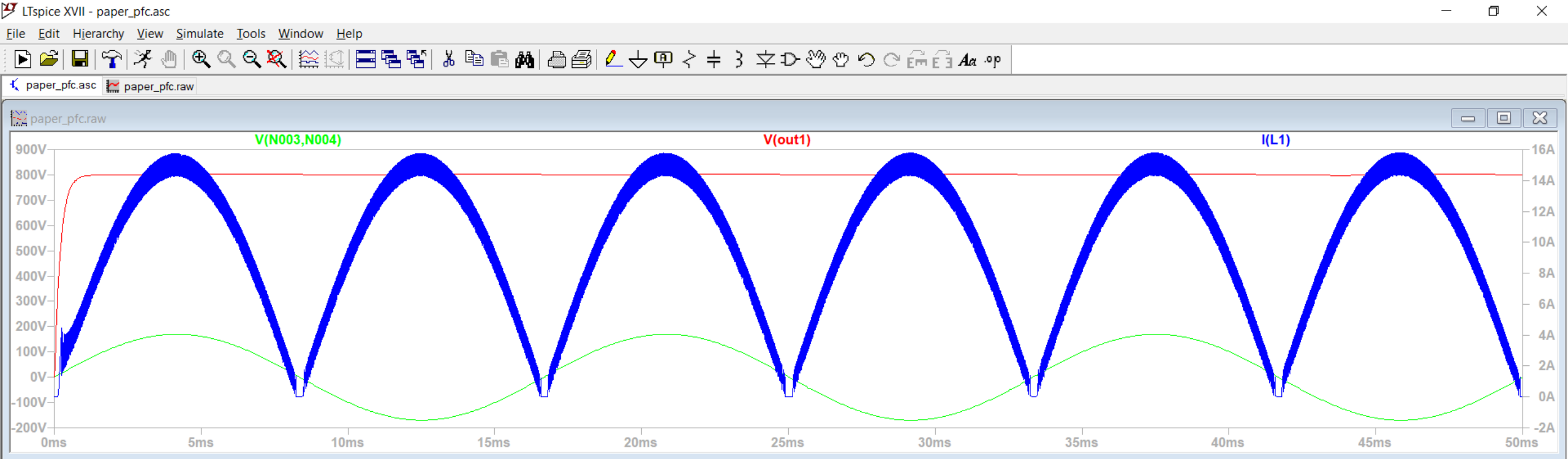
Purpose is to construct a method that is valid for arbitrary V_{acpeak} , V_{dc} , and R_{load} .

- 1) I_L inductor current must follow the reference current within the hysteresis control function. The feedback from I_L is critical here.
- 2) For V_{dc} output feedback, system power must be conserved. Therefore, a V_{out} feedback must be used such that I_L is adjusted to increase or decrease according to V_{out}/V_{dc} . Since $\frac{1}{2} * V_{acpeak} * I_{L_peak} = V_{out}^2 / R_{load}$ via power conservation, any deviation from V_{dc} must cause I_L to correct itself with a factor of the form $(V_{out}/V_{dc})^2$. Using the term $(V_{out}/V_{dc})^2 * I_L$ to replace the I_L term in the hysteresis function would serve the purpose of correction without changing the hysteresis switching condition. For example, if $V_{out} > V_{dc}$, the current I_L would be too large and must reduce so that the term $(V_{out}/V_{dc})^2 * I_L$ would match the reference current. Alternatively, factor $(V_{dc}/V_{out})^2$ can be used to scale I_{ref} . Testing shows they result in similar circuit behavior. But since V_{out} may be accidentally zero so as to blow up the factor, the former factor would be used.
- 3) The reference current used in hysteresis function must obey power conservation such that $\frac{1}{2} * V_{acpeak} * I_{ref_peak} = V_{dc}^2 / R_{load}$. Thus $I_{ref_peak} = 2 * V_{dc}^2 / (R_{load} * V_{acpeak})$.
- 4) To control the average duty cycle and frequency, inductor L can be varied. The smaller the L , the higher the frequency (faster the charging/discharging). The higher the V_{dc} , the higher the average duty cycle and the lower the frequency.





Av. Per= 1.712152861007431E-006
 Av. Freq= 584060.000000000



paper_pfc.asc

More results at Vdc=800V

.PARAM Vacpeak=170
SINE(0 {Vacpeak} 60)
.tran 0 50ms 0 100ns startup uic

.PARAM Rload=500

.PARAM Vdc=800

Av. Period= 4.194630872483222E-006
Av. Freq= 238400.0000000000

.model SW_ini SW(Ron=0.2 Roff=1000k Vt=1)

$$V = 2 * V_{dc} * \frac{2}{(R_{load} * V_{acpeak})}$$

$$V = V(Ref) + V(PWM) * V(In) * Hyst_{Ref2}$$

$$V = V(In) * ABS(\sin(2 * \pi * 60 * Time))$$

$$V = \tanh(Gain * (V(Hyst_Ref) - ((V(out1) - V(out2)) / V_{dc}) * 2 * V(Fedb)))$$

.PARAM Hyst = 0.05
.PARAM Gain = 500

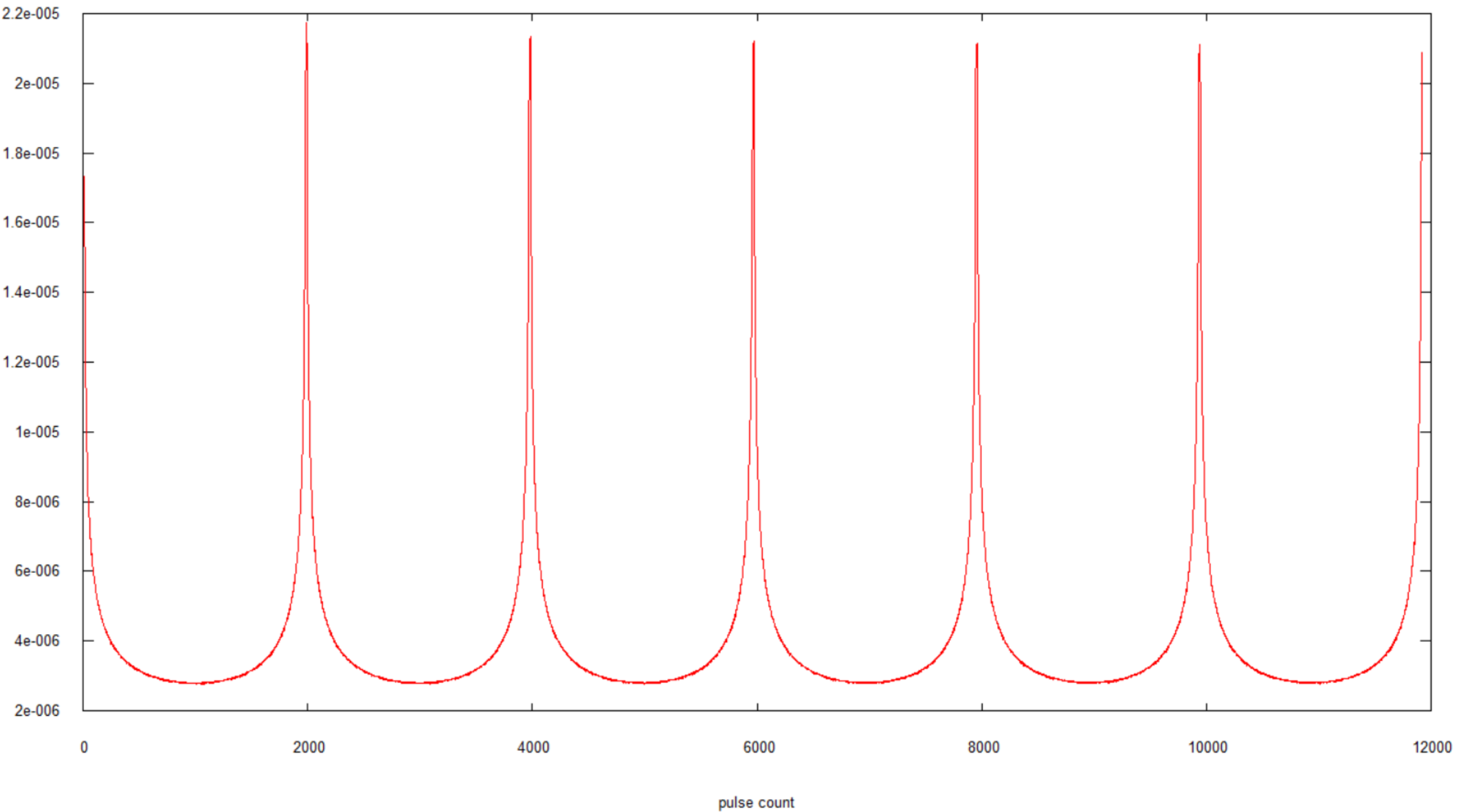
gnuplot pause

OK

OK Cancel

Switching period

period

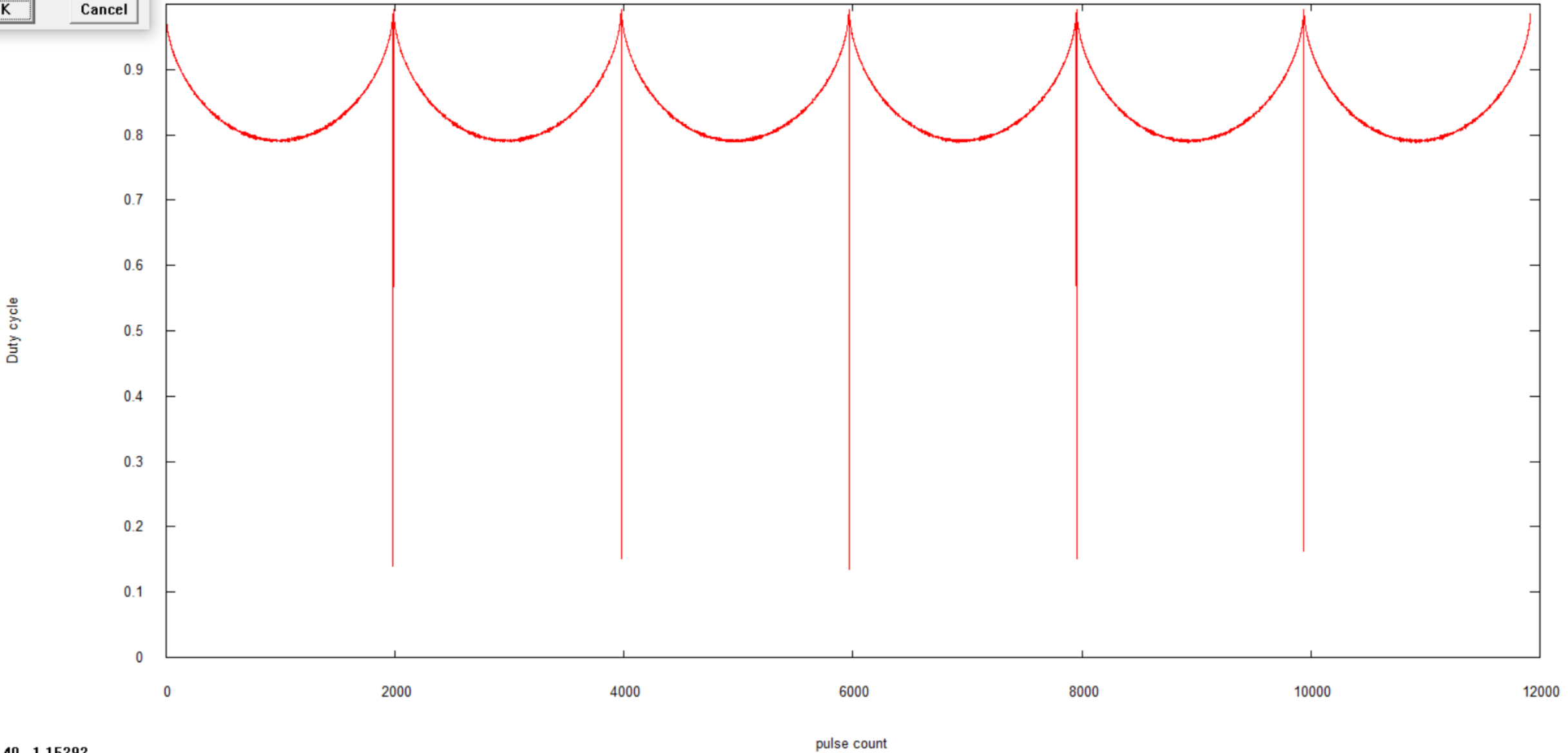


gnuplot pause

OK

OK Cancel

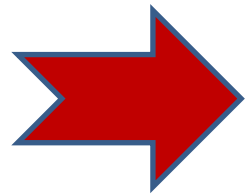
PWM duty cycle



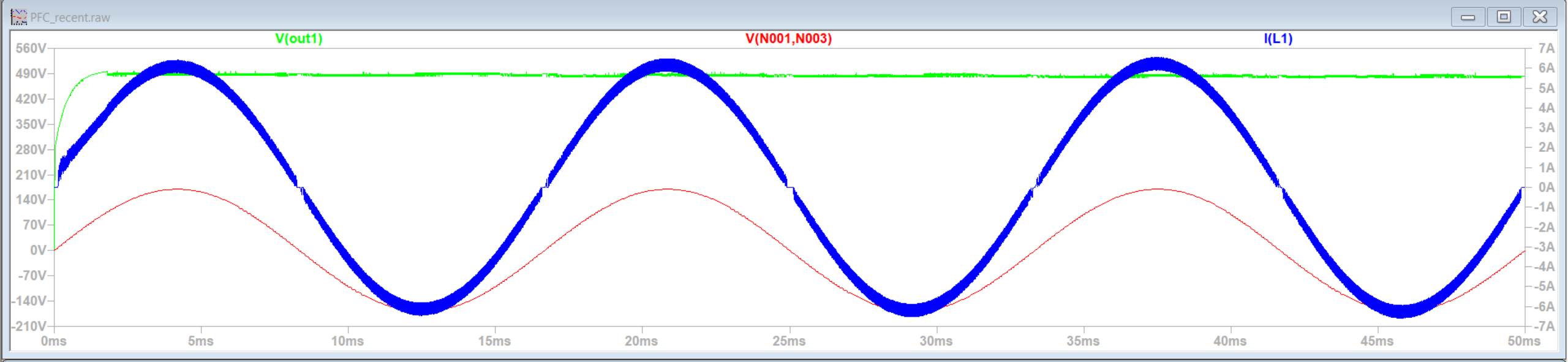
Content

Simulation of inductor current control

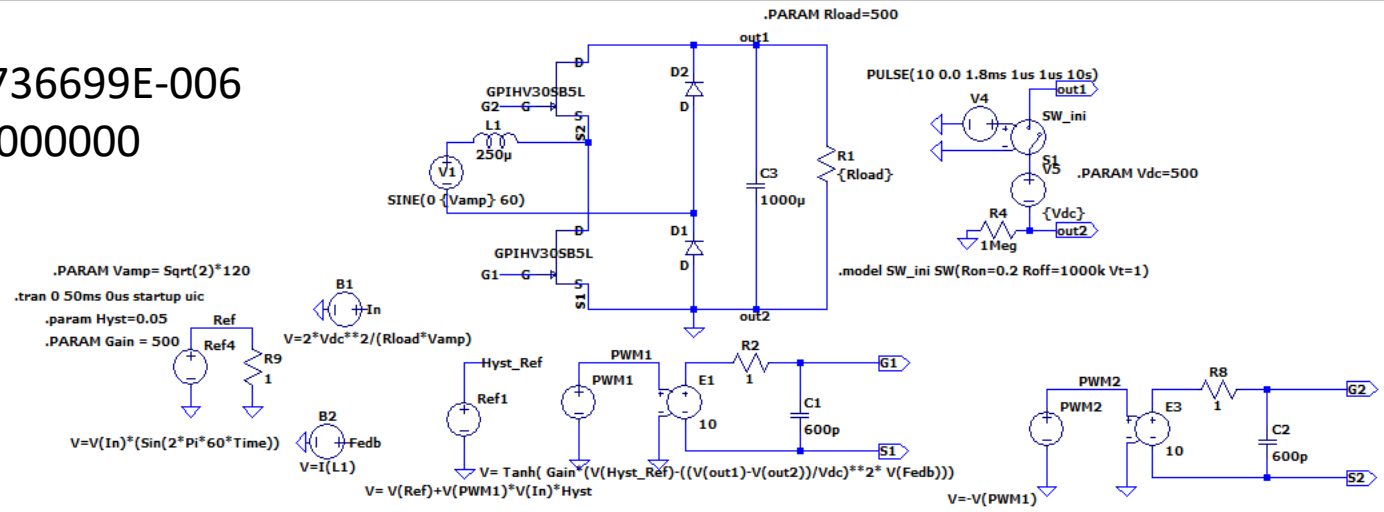
Circuit implementation

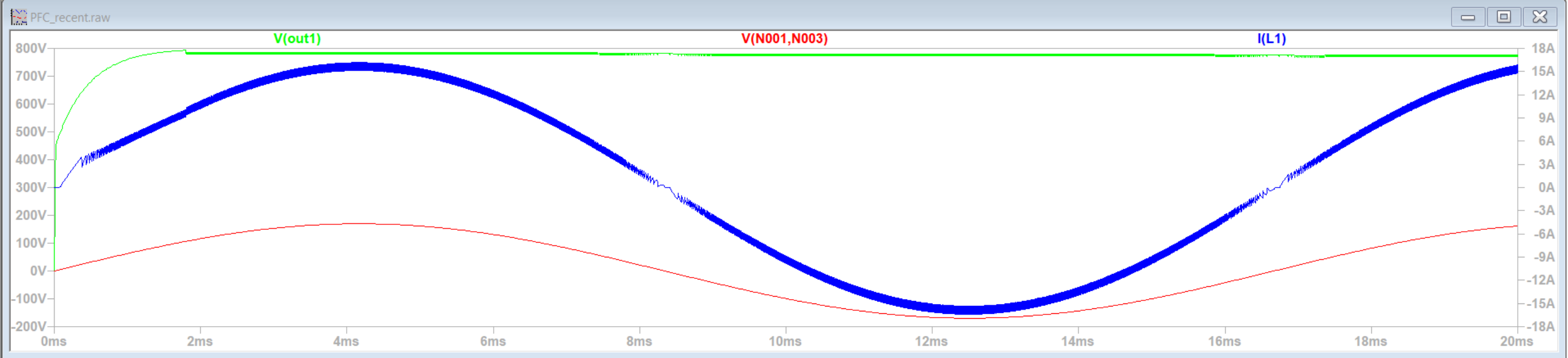


Totem pole PFC

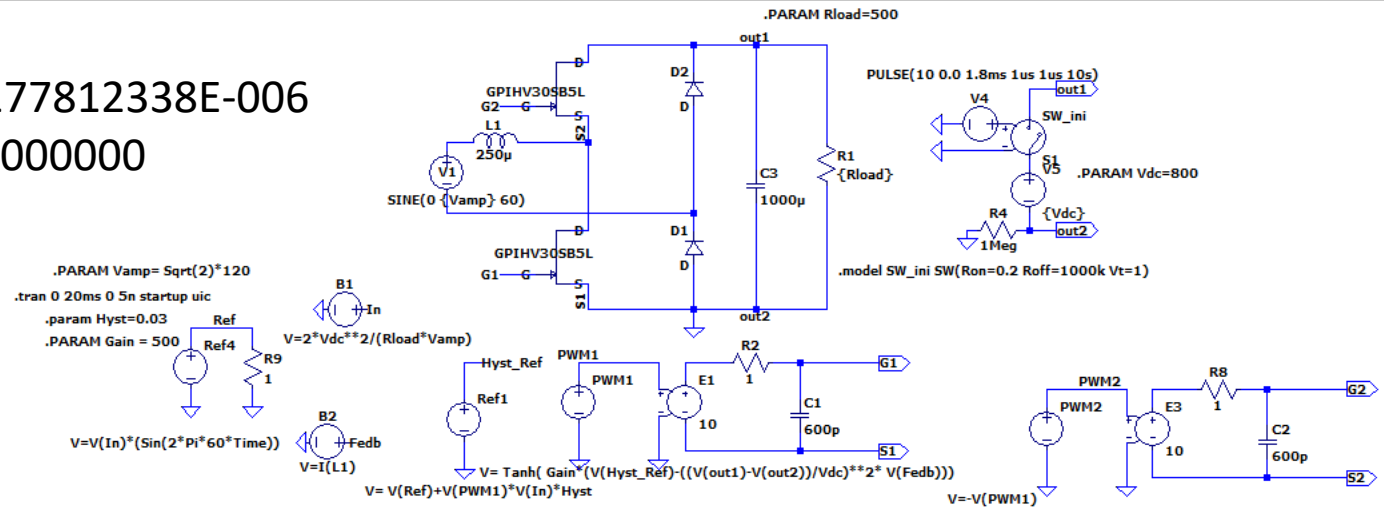


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 Av. Freq= 472160.000000000

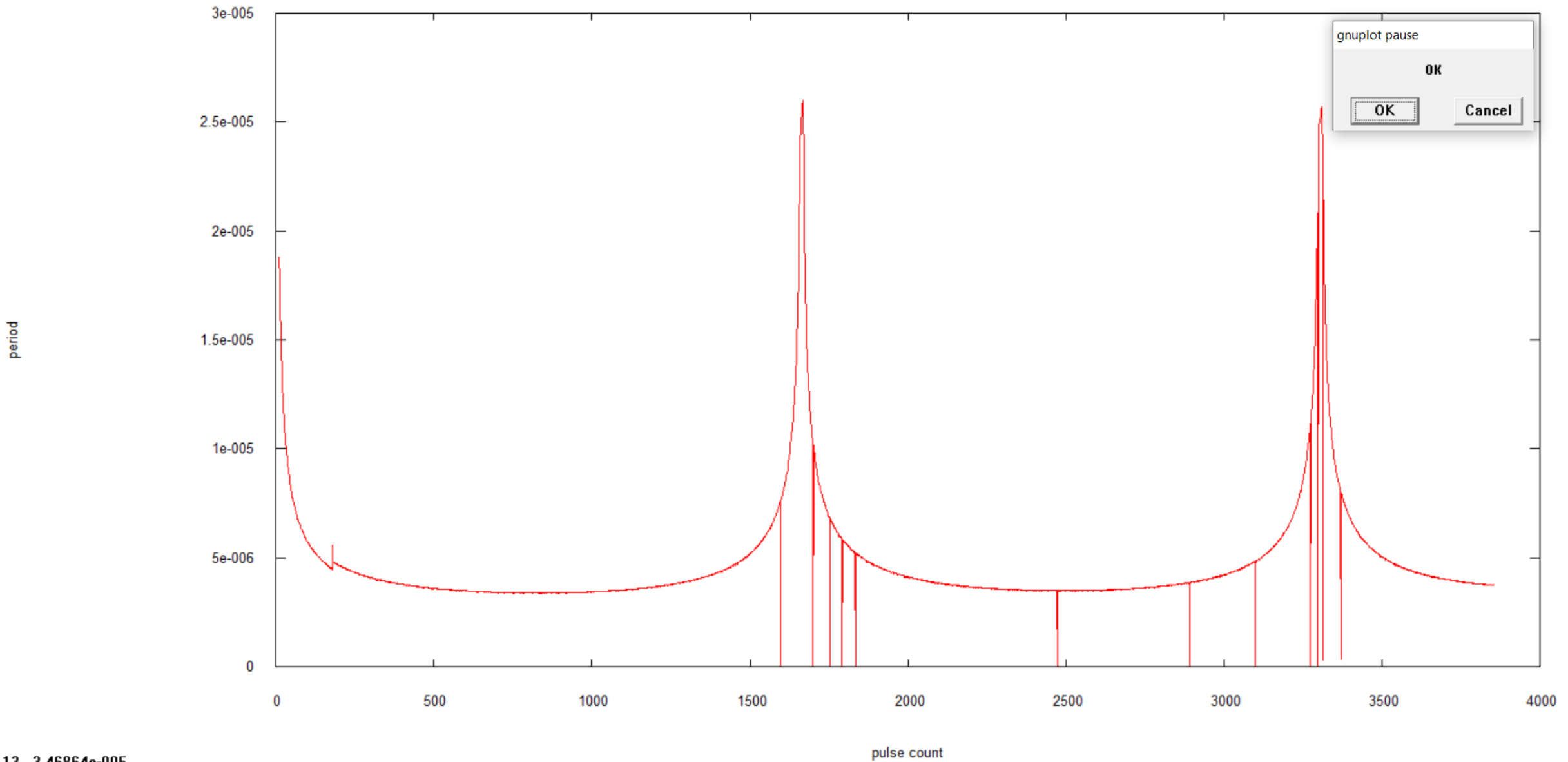




Av. Period= 5.184033177812338E-006
 Av. Freq= 192900.000000000

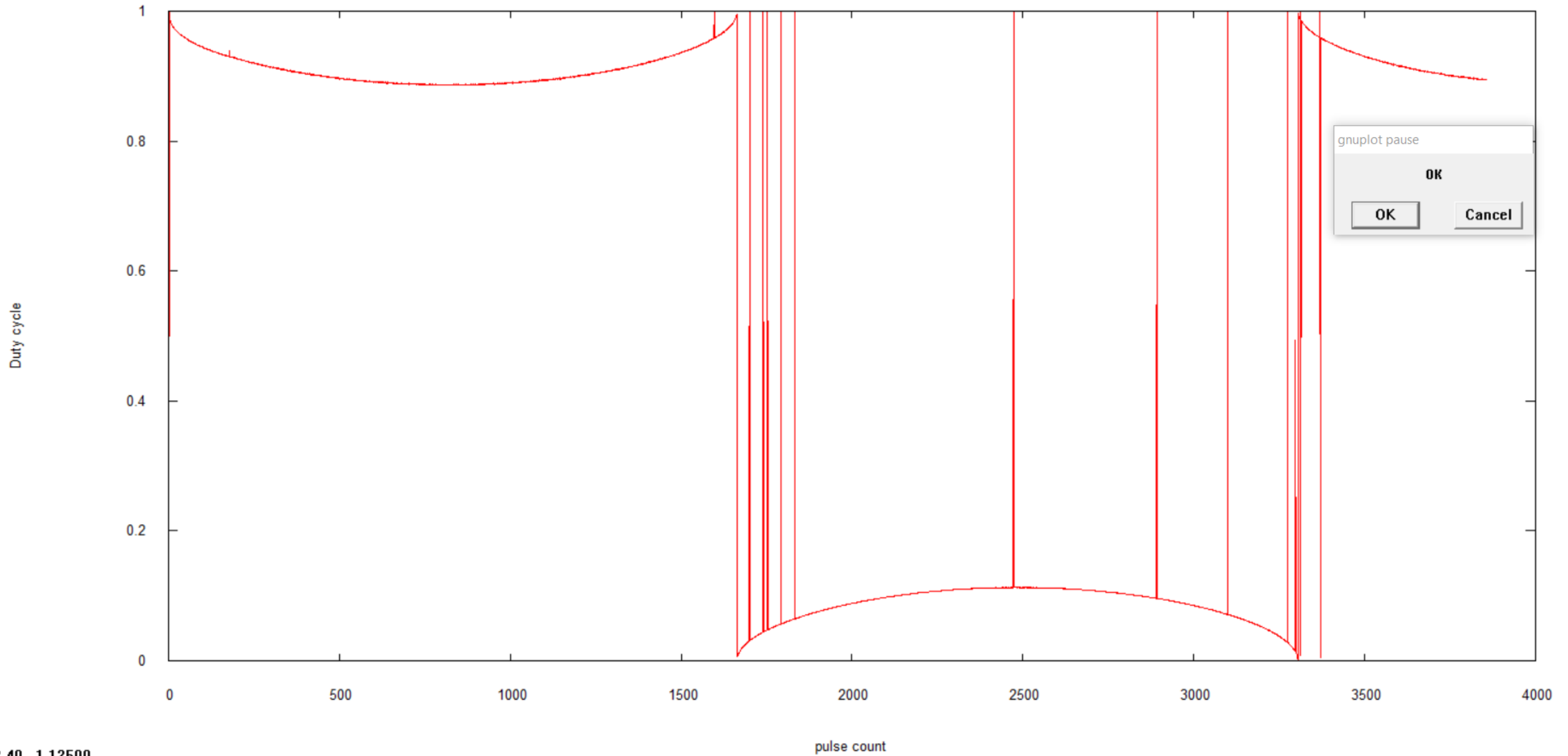


Switching period



3069.13 3.46864e-005

PWM duty cycle



Summary

- Using LTSpice simulator, Boost PFC and totem Pole PFC can be designed using GaNPower 1200V GaNFET
- Circuit implementation takes feedbacks from output voltage and inductor current in a form easy to implement using op-amp or digitally controlled using the $\tanh()$ function.

LET'S WORK TOGETHER

Our Believes

Integrity

Technology Innovation

Fast Growing



THANKS FOR YOUR PATIENCE AND SUPPORT
衷心感謝您的耐心與支持